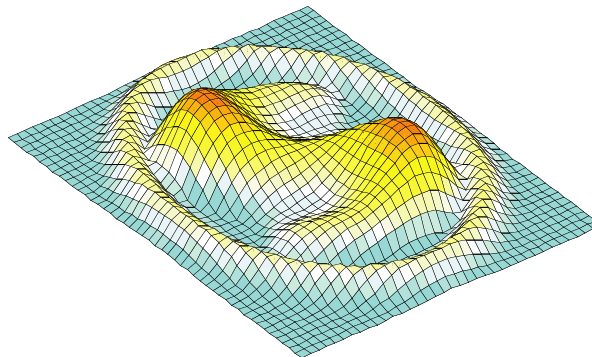


# Surface Operation Automation Research — SOAR —

**Dr. Victor H. L. Cheng**  
**Optimal Synthesis Inc.**  
**Los Altos, California**

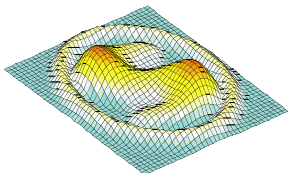
**Virtual Airspace Modeling and Simulation (VAMS)**  
**Air Transportation System Capacity-Increasing Research**  
**Technical Interchange Meeting**  
**January 14–15, 2003**



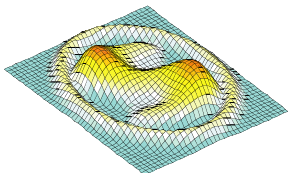
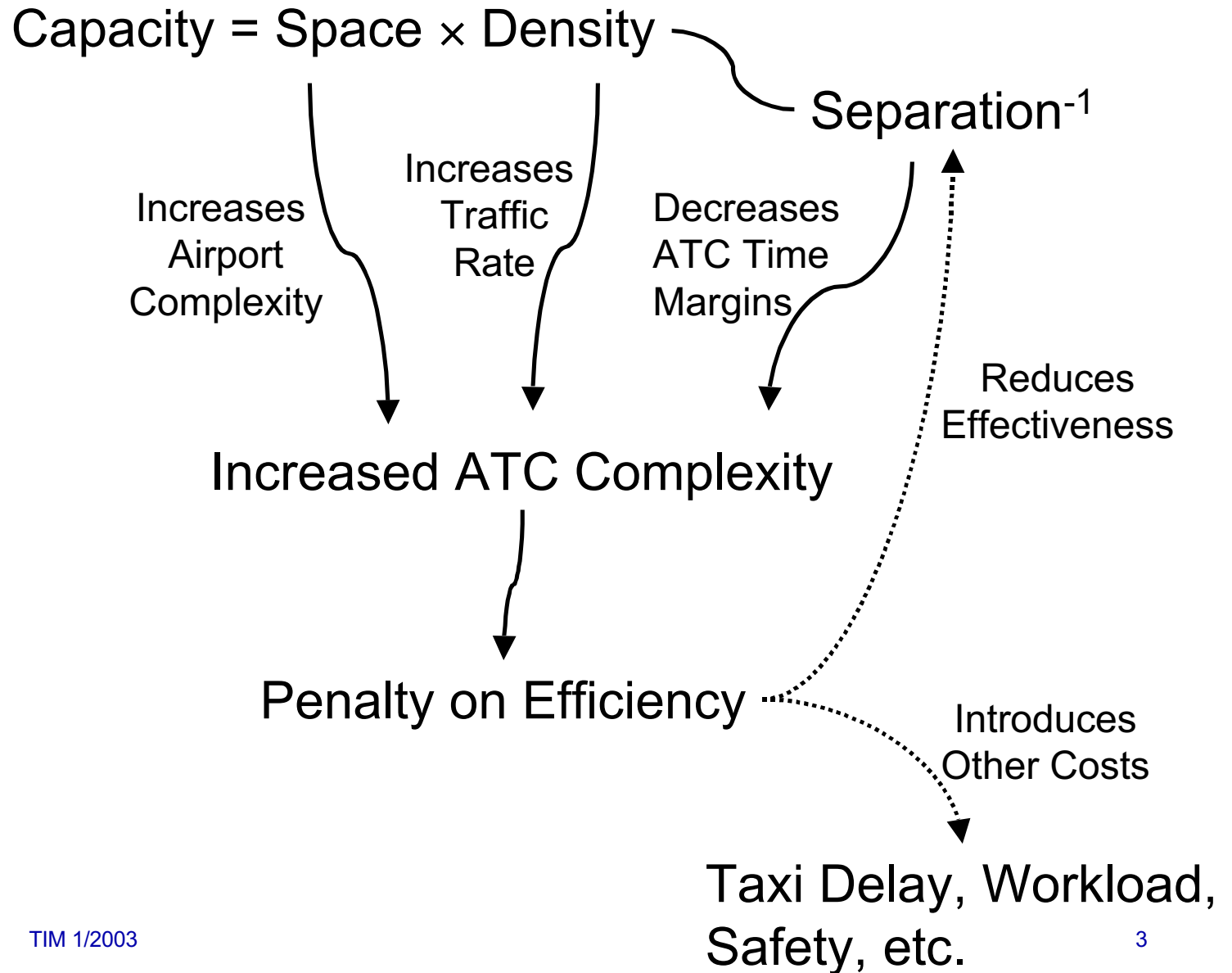
# Outline

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- **Airport Capacity Enhancement Issues**
- **SOAR Concept**
- **ATM Automation Functions**
- **Flight-Deck Automation Functions**
- **Integrated Operation of SOAR Systems**
- **System Performance**
- **Human Performance**
- **Concept Development and Technology Roadmap**



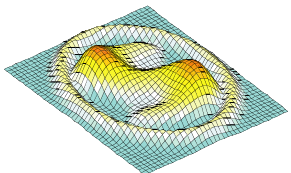
# Airport Capacity Enhancement Issues



# Quantitative Goals

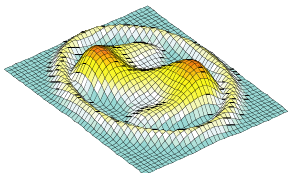
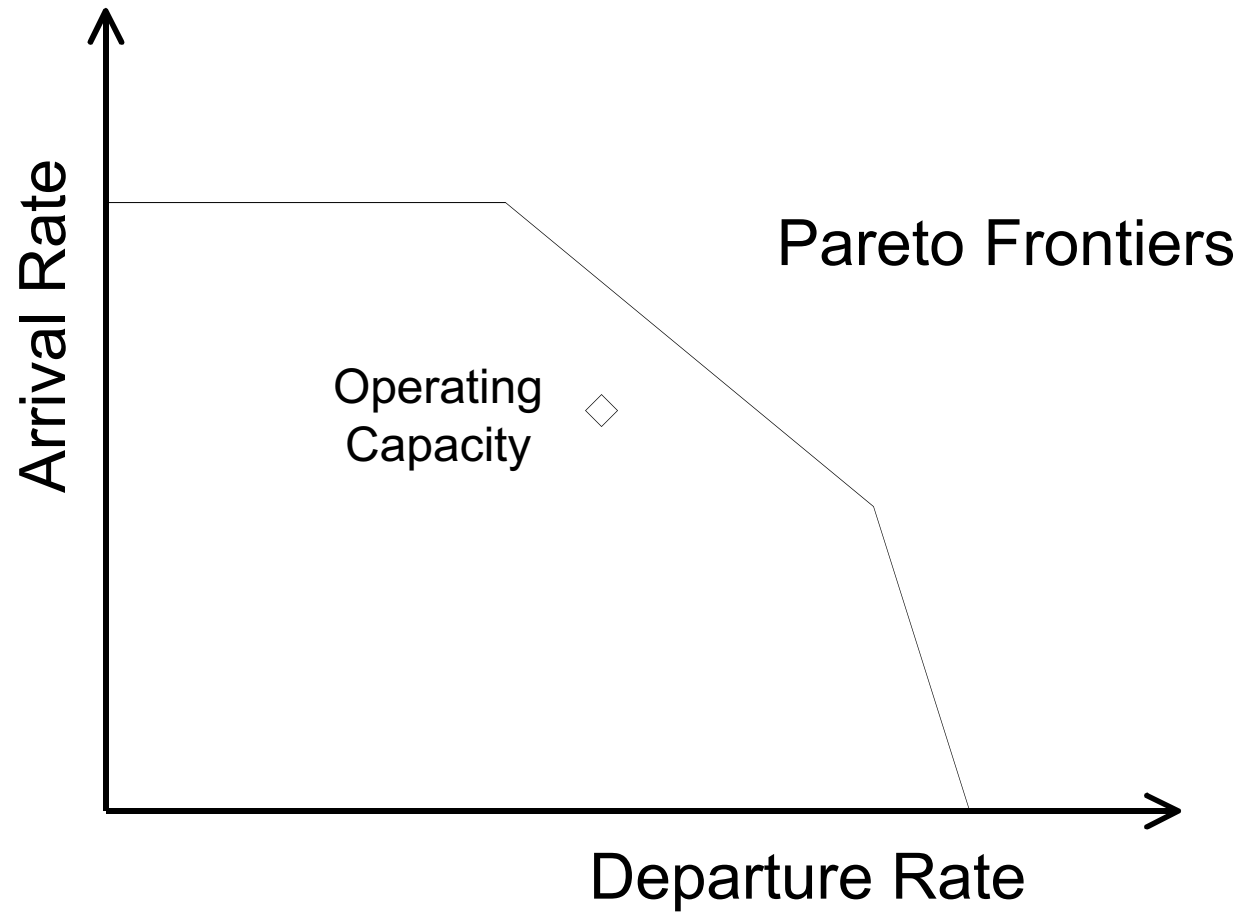
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- **Bi-objective airport capacity problem: Pareto frontiers describe balance between departure and arrival traffics.**
- **Achievable airport capacity can be maximized by lowering priorities of other surface traffic: undesirable taxi delays.**
- **SOAR concept seeks enhancement with tradeoff between two efficiency factors:**
  - Reduction in achievable traffic rate, a penalty on arrival/departure efficiency
  - Increase in taxi delay, a penalty on surface traffic efficiency
- **Quantitative goals: enhance and strike balance between these efficiency factors, e.g. simultaneously**
  - achieve 90% of the ideal airport capacity
  - maintain cumulative delay to within 10% of the cumulative ideal taxi time



# Bi-objective Capacity Optimization

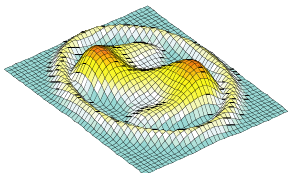
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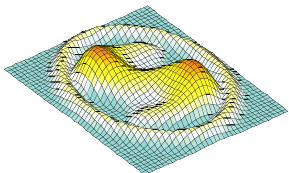
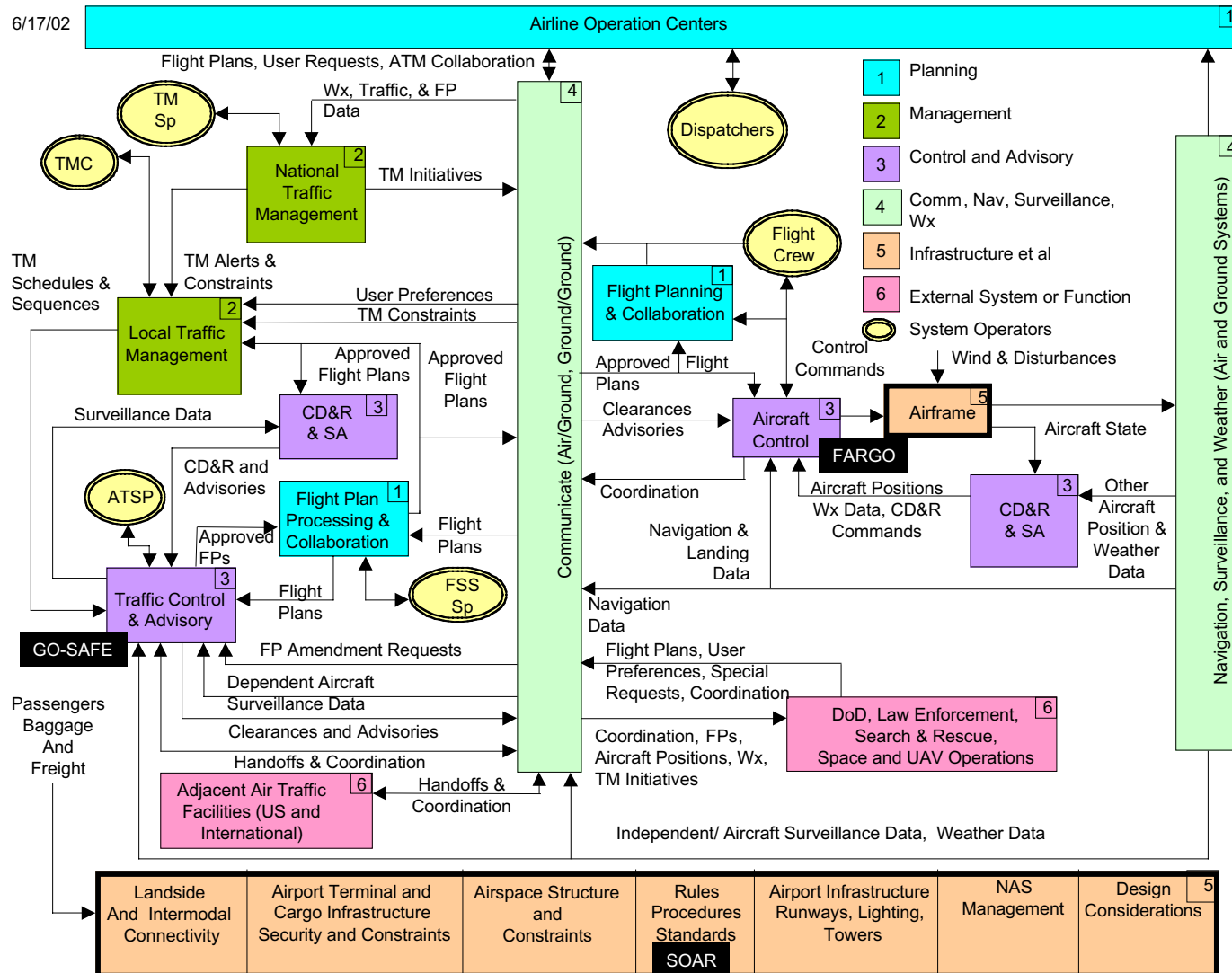
# SOAR Concept

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- **Advanced automation in Centralized Decision-making, Distributed Control (CDDC) paradigm**
- **Centralized Decision-Making: Ground-Operation Situation Awareness and Flow Efficiency (GO-SAFE) for Surface Traffic Management (STM) Automation**
  - Basic functions studied under previous SBIR Phase II effort
- **Distributed Control: Flight-deck Automation for Reliable Ground Operation (FARGO) for Flight Deck Automation**
  - Feasibility of high-precision taxi control demonstrated in previous SBIR Phase I study
- **Integrated operation of both systems**
  - GO-SAFE to help issue efficient time-based taxi clearances
  - FARGO to help execute taxi clearances



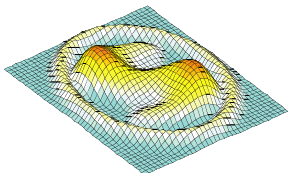
# GFI Model with SOAR Technology Components



# STM Automation Functions

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- **User interface, including situational display for monitoring surface traffic, and alerting of impending problems**
  - Updated to allow easy reconfiguration to support Phase II evaluations
- **Taxi-route generation and editing**
  - Previous taxi-route generation based on dynamic programming for route optimization
  - GO-SAFE software architecture allows inclusion of multiple route-generation techniques
  - Route editing functions enabled by GUI: end-point change, route change, timing change
- **Conflict detection and resolution**
- **Decision support tool for efficient and safe operation**





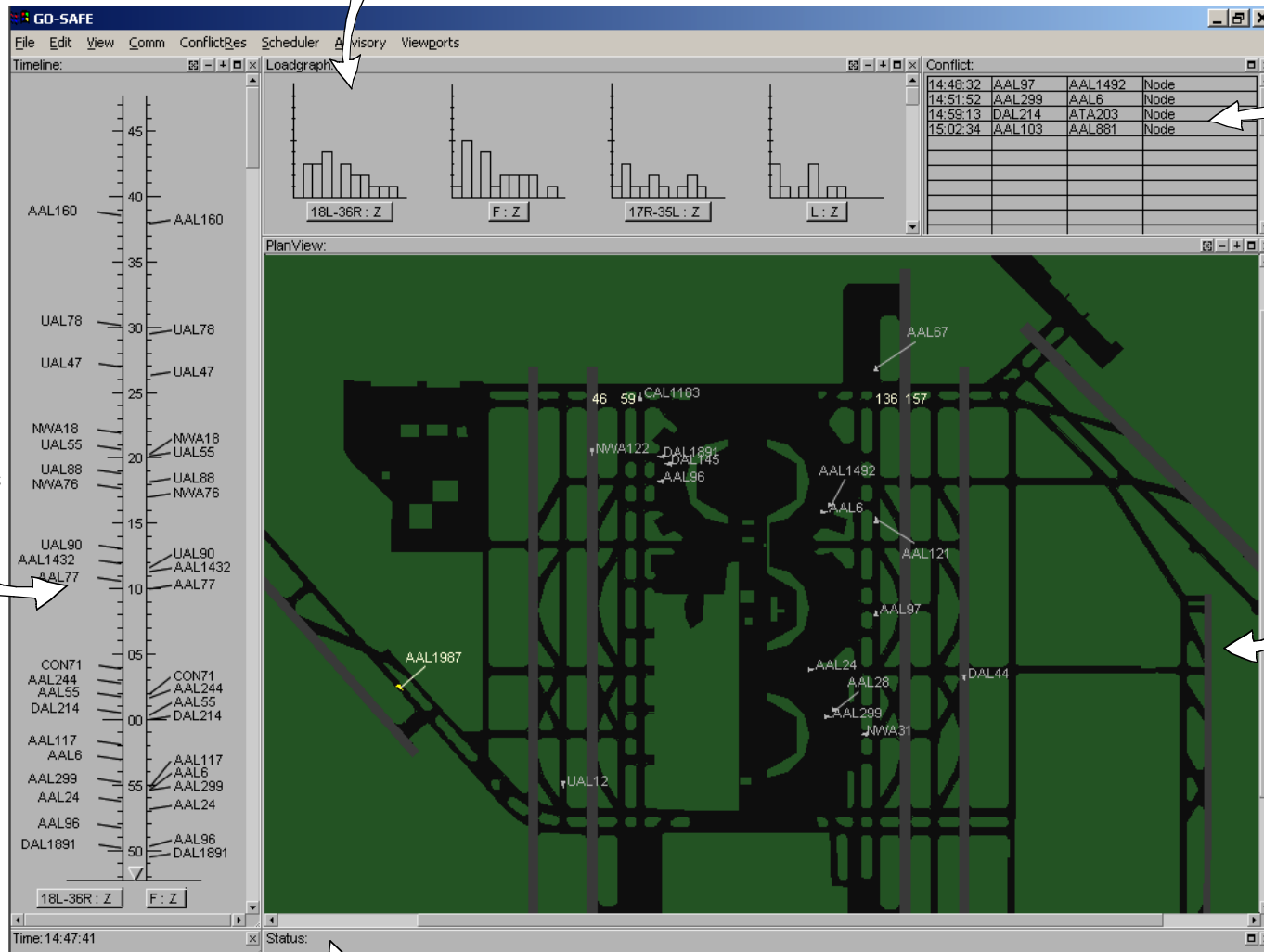
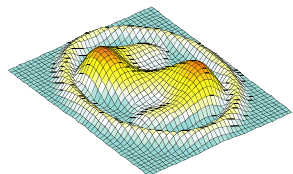
# Overview of GO-SAFE GUI

Node-Traffic Load Graphs

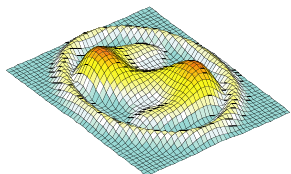
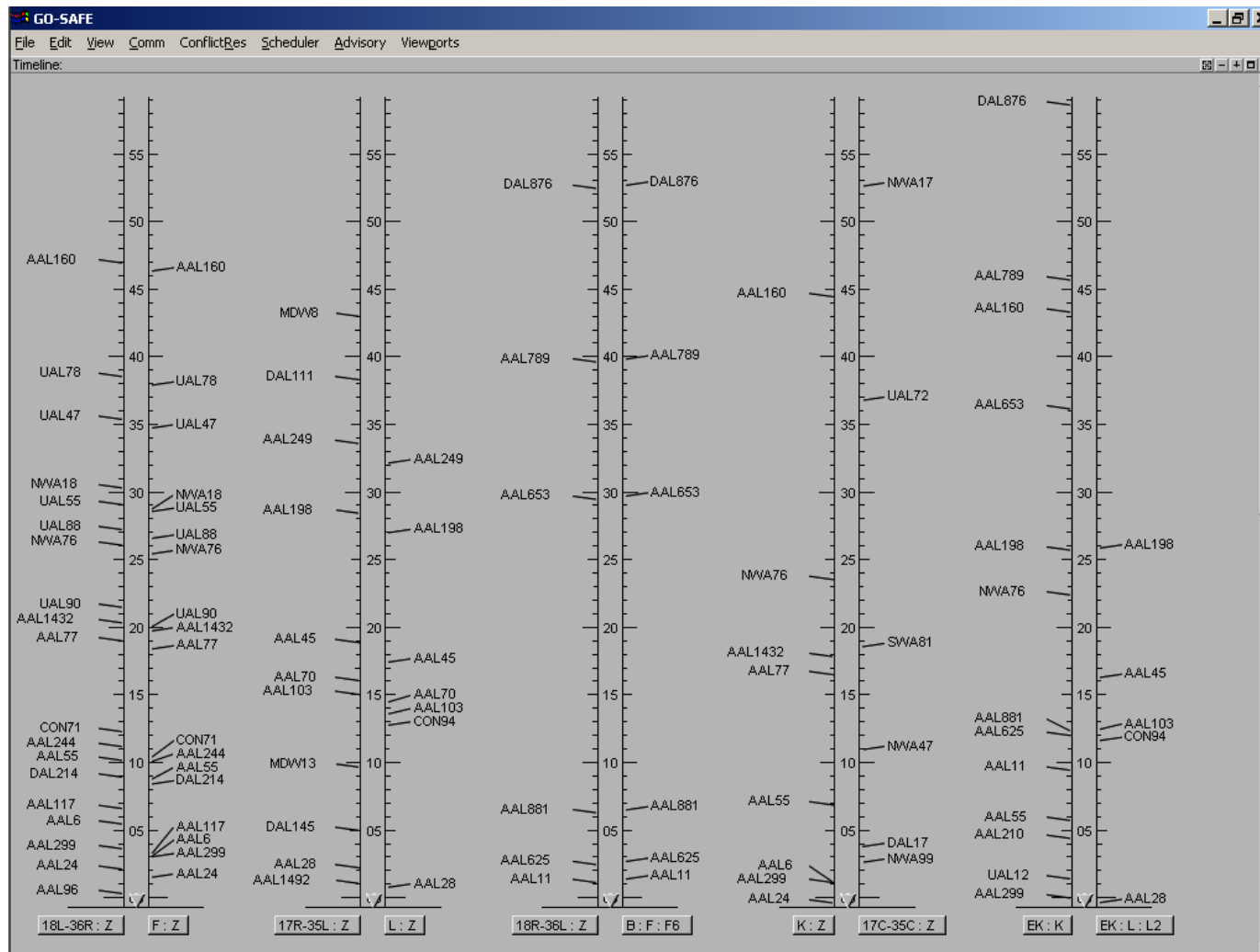
Node-Traffic Time Lines

Conflict Information

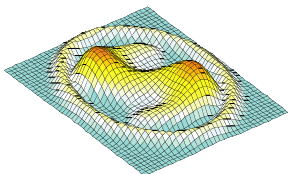
Plan-View Display



# Sample Full-Screen Time-Line Display



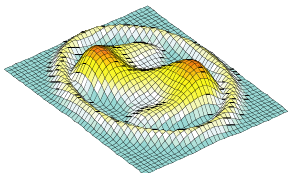
# Sample Full-Screen Load-Graph Display



# Conflict Detection and Resolution

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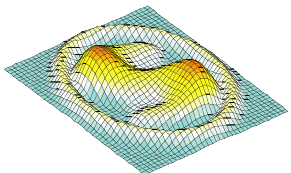
- Requirements for conflicts on airport surface not as serious as for IFR flights: in current operations, cockpit crew is responsible for separation while taxiing.
- Conflicts of taxi routes in internal representations of GO-SAFE can be resolved
  - Manually by controller through route editing
  - Automatically by GO-SAFE with timing changes
- All time-based taxi routes must be conflict-free.
- Clearances composed of conflict-free routes will facilitate detection of real-world conflicts
  - Any conflicts caused by flights with cleared routes must mean the flights have deviated from the routes.



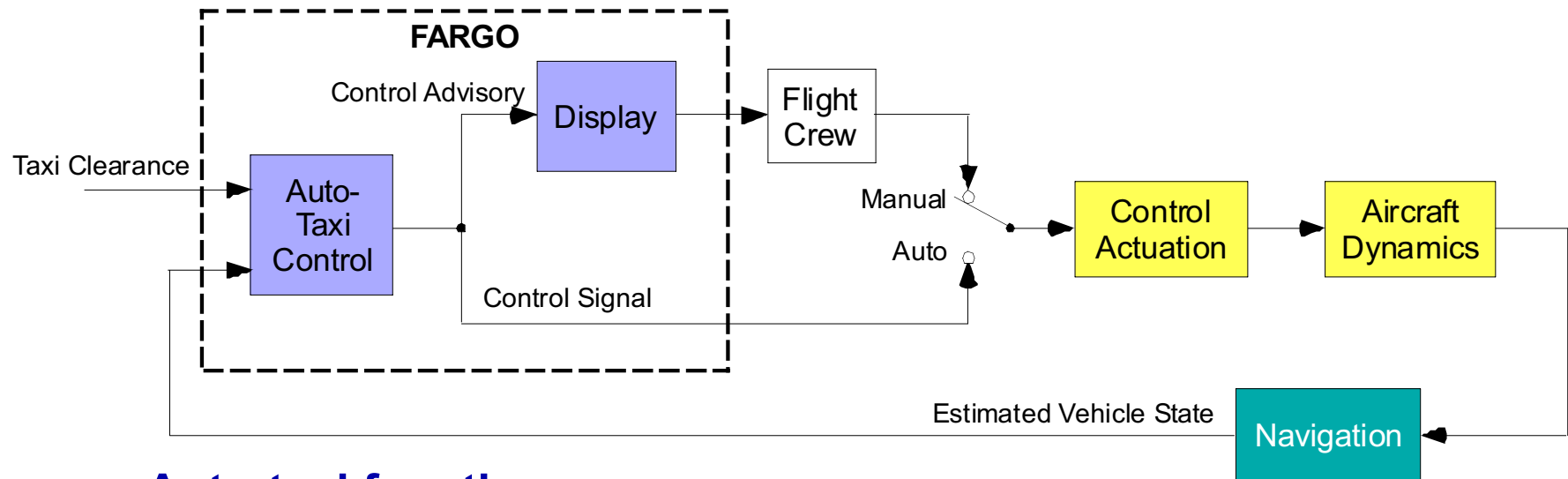
# Decision Support System

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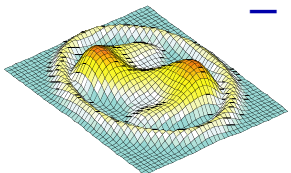
- **Surface Resource Scheduler**
  - Runway usage for landing, takeoff and crossing traffic
  - Other surface resources: special facilities (e.g. de-icing), identified choke points
- **Clearance Manager**
  - Manages and issues advisories/clearances
  - Encodes clearances according to route definition, including crossing time restrictions
  - Monitors clearances and flight clearance status
  - Assists with route changes: “what-if” capability to predict impact of modified routes
- **Conformance Monitor**
  - Monitors aircraft compliance with clearances
  - Detect incursions and conflicts with other flights or ground vehicles



# Flight-Deck Automation Functions

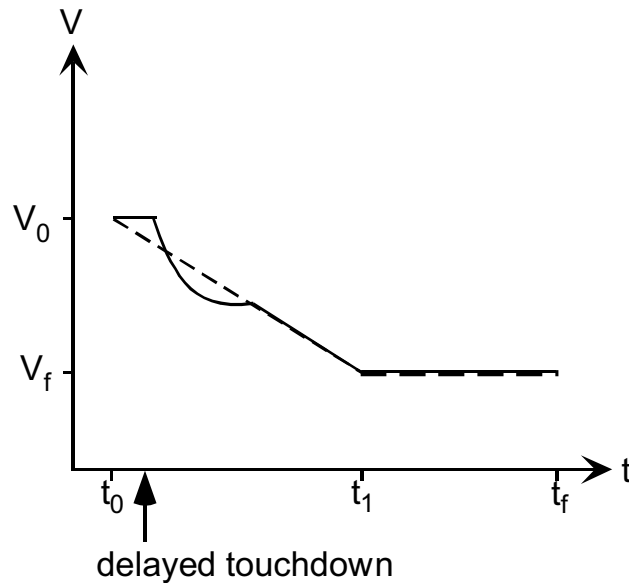


- **Auto-taxi function**
  - Precise control of aircraft taxi to execute clearance
  - Potential use of time-based taxi routes, decoded from clearance
  - Guidance signal for driving pilot interface
- **Pilot interface to allow the pilots to perform precision-taxi**
  - Far-term: fully automatic taxi
  - Near-term: control signals generated by the auto-taxi function to direct manual control

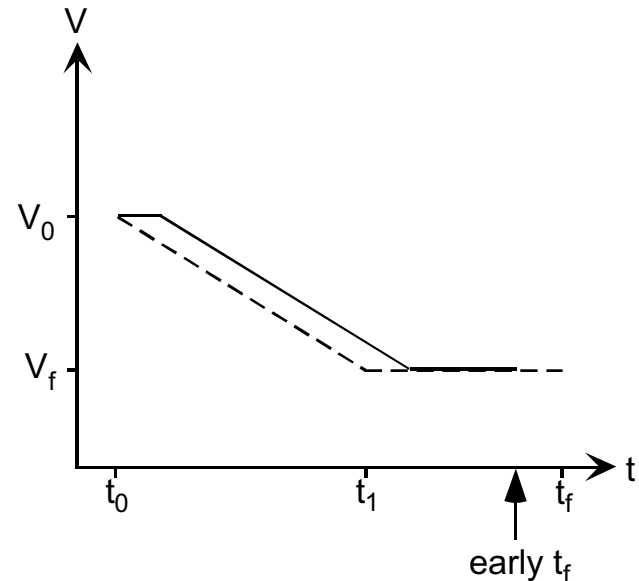


# Auto-Taxi Control

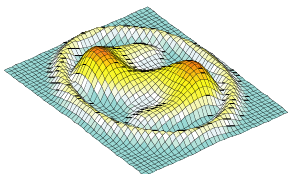
- Nominal guidance assures passenger comfort and safety.
- Must be robust in off-nominal situations: e.g. prolonged flare during landing.



- Excessive deceleration

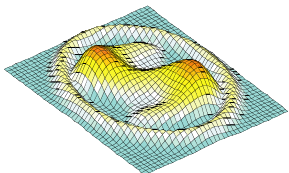
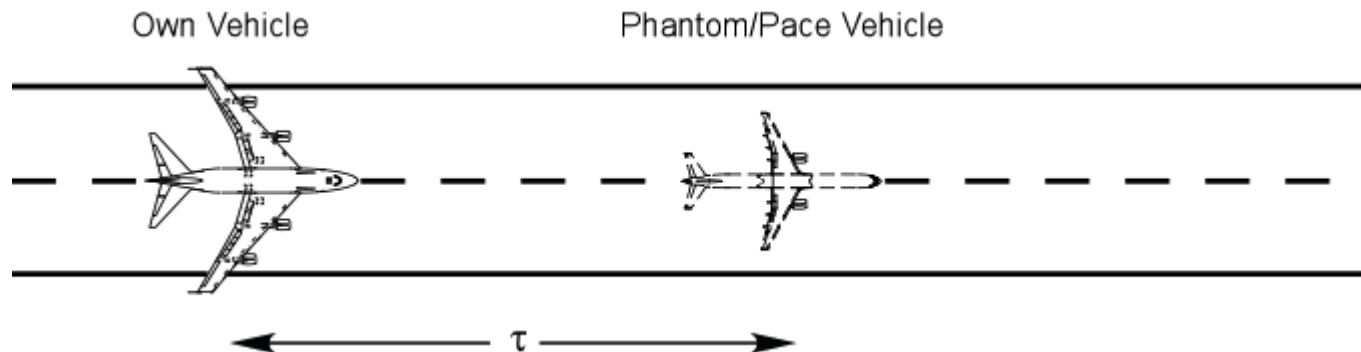


- Speed too high at turnoff
- Arrival too early at scheduled intersection



# Pilot Interface Considerations

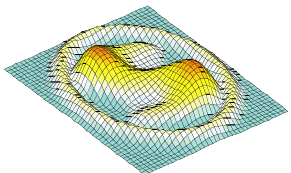
- Traditional flight director with speed bug is unsuitable.
- Pace-vehicle concept allows separation to increase with speed.
- Special consideration needs to be given to
  - Acceleration/deceleration
  - Stop/go events
- Suitable for HUD implementation: integration with T-NASA



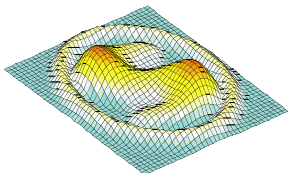
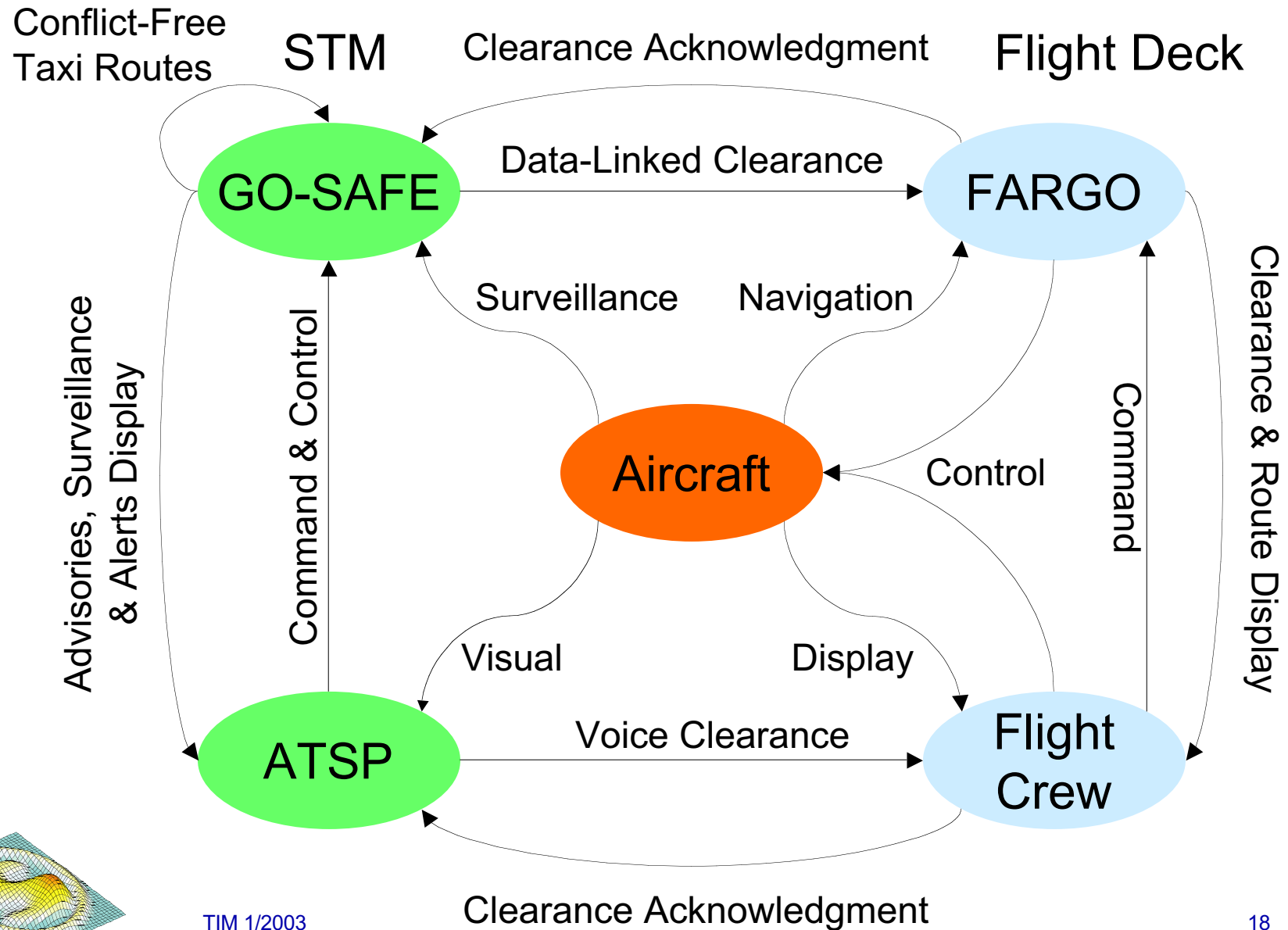


# T-NASA Displays

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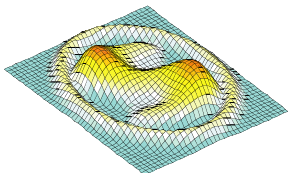
# Integrated Operation of SOAR Systems



# Operational Implications of SOAR Concept

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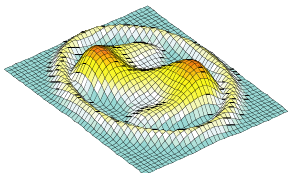
- **Complex taxi routes with time constraints  $\Rightarrow$  data-link clearances preferred over voice communication**
- **Tower controller**
  - Cannot expect immediate acknowledgment
  - Will likely use pre-clearances
- **Flight crew**
  - Cockpit crew may be distracted from flight control
    - Reading out clearances for agreement between crew members
    - Understanding details of time-based routes
    - Responding via console input
  - Route information can be more easily entered into FMS.
- **Use of data-link clearances with encoded taxi routes may change hand-off procedure between local controller and ground controller.**



# System Performance

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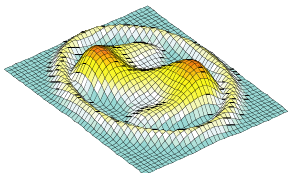
- **Common Performance Factors**
  - Achievable landing and departure rates
  - Surface traffic efficiency in terms of taxi delays
  - Workload
  - Safety
- **GO-SAFE**
  - Scheduler effectiveness
  - Taxi routes: efficient and conflict free
  - Conformance monitor: warning signs of separation violations
  - Controller-interface effectiveness
- **FARGO**
  - Taxi-control effectiveness
  - Pilot-interface effectiveness
  - Conflict detection using ADS-B and TIS-B



# Performance Evaluation

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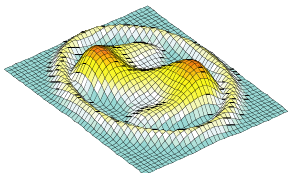
- **Field Tests: Ultimate operational evaluations**
- **High-Fidelity Simulations**
  - GO-SAFE, PAS or GO-Sim, Aircraft Simulation + FARGO
  - Potentially human in the loop
  - Suitable for evaluation of system and human performance
- **Mid-Fidelity Simulations**
  - GO-SAFE to schedule and sequence flights, with taxi-route generation to predict timing
  - Operator latency and accuracy can be included in computation
  - Suitable for studying impact of surface traffic on arrival/departure traffics, interface with TRACON traffic
- **Low-Fidelity Simulations**
  - Empirical formulation of runway capacity for arrival and departure traffics
  - Suitable for assessing impact on system-wide concepts



# Human Performance

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- **Human-Factors Analyses**
  - Human-factors experts critiquing individual design features and operational procedures
- **Human-in-the-Loop Simulations**
  - Controllers evaluating GO-SAFE and pilots evaluating FARGO
  - Pseudo-pilots operating PAS or GO-Sim to increase traffic realism
- **Computer Simulations**
  - Human behaviors too complex to be adequately modeled in computer simulations
  - Possible to identify required human operator actions in accordance with operational procedures
  - Actions modeled in simulation and data collected
  - Post-simulation analyses to include time and effort considerations in performing required actions, to assess human performance in executing procedures



# Concept Development and Technology Roadmap

